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# BlueROV2

TETHER		
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Diameter	7.6 mm	0.30 in
Length	25-300 m	80-980 ft
Working Strength	45 kgf	100 lbf
Breaking Strength	160 kgf	350 lbf
Strength Member	Kevlar with waterblock	
Buoyancy in Freshwater	Neutral	
Buoyancy in Saltwater	Slightly positive	
Conductors	4 twisted pairs, 26 AWG	

# LIGHTS

Brightness	2 or 4 x 1500 lumens each with dimming control
Light Beam Angle	135 degrees, with adjustable tilt

#### CAMERA

Camera	1080p digital
Camera Field of View	110 degrees horizontally
Tilt Range	+/- 90 degree camera tilt (180 total range)
Tilt Servo	Hitec HS-5055MG

#### **BATTERY** (CAN BE CHANGED IN ABOUT 30 SECONDS)

Battery Life (Normal Use)	2-3 hours w/ 18Ah battery
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#### **SENSORS**

3-DOF Gyroscope
3-DOF Accelerometer
3-DOF Magnetometer
Internal barometer
Blue Robotics Bar 30 Pressure/Depth & Temperature Sensor (external)
Current and Voltage Sensing
Leak Detection

### **PRODUCT FEATURES**

Live Low-Latency 1080p HD Video
Highly Maneuverable Vectored Thruster Configuration
Stable and Optimized for Inspection and Research-Class Missions
Easy to Use, Cross-Platform User Interface
Highly Expandable with Three Free Cable Penetrators
T200 Thrusters and Basic ESCs
Standard 100m Depth Rating and up to 300m Tether Available
Battery Powered with Quick-Swappable Batteries for Long Missions
Open-Source ArduSub Control Software and Open-Source Hardware

PHYSICAL				
	<b>▼</b>			
Length	457 mm	18 in		
Width	338 mm	13.3 in		
Height	254 mm	10 in		
Weight in Air (with Ballast)	10-11 kg	22-24 lb		
Weight in Air (without Ballast)	9-10 kg	20-22 lb		
Net Buoyancy (with Ballast)	0.2 kg	0.5 lb		
Net Buoyancy (without Ballast)	1.4 kg	3 lb		
Watertight Enclosure Inner Diameter	102 mm	4 in		
Watertight Enclosure Inner Length	298 mm	11.75 in		
Cable Penetrator Holes	14 x 10 mm	14 x 0.4 in		
Construction	HDPE frame, aluminum flanges/end cap, & acrylic tubes			
Main Tube (Electronics Enclosure)	Blue Robotics 4" Series w/ aluminum end caps			
Battery Tube	Blue Robotics 3" Series w/ aluminum end caps			
Buoyancy Foam	R-3318 urethane foam r	ated to 210 m		
Ballast Weight	6 x 200 g coated lead we	eights		
Battery Connector	XT90			

## PERFORMANCE

Maximum Rated Depth	100 m	330 ft
Maximum Tested Depth (so far)	130 m	425 ft
Maximum Forward Speed	1 m/s	2 knots
Thrusters	Blue Robotics T200	
ESC	Blue Robotics Basic 30A ESC	
Thruster Configuration	6 thrusters	
	- 4 Vectored	
	- 2 Vertical	
Forward Bollard Thrust	14 kgf	30 lbf
Vertical Bollard Thrust	9 kgf	20 lbf
Lateral Bollard Thrust	14 kgf	30 lbf



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